

Classification of Lotka-Volterra cubic systems with 1:-2 singularity and straight lines of three directions and total multiplicity six

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We consider the real Lotka-Volterra cubic system of differential equations with 1:-2 singularity

$$\begin{aligned} \dot{x} &= x(a_{30}x^2 + a_{21}xy + a_{12}y^2 + a_{20}x + a_{11}y + 1) \equiv P(x, y), \\ \dot{y} &= y(b_{21}x^2 + b_{12}xy + b_{03}y^2 + b_{11}x + b_{02}y - 2) \equiv Q(x, y), \end{aligned} \quad (1)$$

where $\gcd(P, Q) = 1$. In this paper we give a classification of systems (1) with six invariant straight lines of three directions.

Theorem 1. *The system (1) has invariant straight lines of three directions of total algebraic multiplicity six if and only if it has one of the following twelve forms :*

- 1) $\dot{x} = -x(x-1), \dot{y} = y(y-1)(2-x-y)$;
 - 2) $\dot{x} = x(1-axy + (1+d)y^2 + ax), \dot{y} = y(y-1)(dy+2)$;
 - 3) $\dot{x} = x(x-1)(ax-1), \dot{y} = y(-2+3x+dy + (a-2)x^2 - dxy)$;
 - 4) $\dot{x} = \frac{1}{4}x(4+f^2x^2 + 4fxy + 4(1+c)y^2 - 4fx), \dot{y} = y(y-1)(2+cy)$;
 - 5) $\dot{x} = \frac{1}{4c^2}x(4f^2x^2 + 4c^2fxy + c^3(4+c)y^2 + 8cfx + 4c^2),$
 $\dot{y} = y(y-1)(cy+2)$;
 - 6) $\dot{x} = x(x-1)(ax-1),$
 $\dot{y} = -\frac{1}{8a^2}(16a^2 - 24a^3x - 8a^3(1+2a)x^2 + 8afy - 8a^2fxy + f^2y^2)$;
 - 7) $\dot{x} = x(x-1)(ax-1),$
 $\dot{y} = -\frac{1}{8}y(f^2y^2 - 8fxy + 8(2-a)x^2 - 24x + 8fy + 16)$;
 - 8) $\dot{x} = \frac{1}{4}x(f^2x^2 + 4fxy - 4y^2 - 4fx + 4), \dot{y} = -2y(y-1)^2$;
 - 9) $\dot{x} = x(x-1)^2, \dot{y} = -\frac{1}{b^2}y(2b^2 - 3b^2x + b^2x^2 - 4by + 4bxy + 2y^2)$;
 - 10) $\dot{x} = \frac{1}{2}x(x-1)((2+c)x-2), \dot{y} = \frac{1}{2}y(y-1)(4-(4+c)x+2cy)$;
 - 11) $\dot{x} = \frac{1}{2+c}x(x-1)(-2+2x-c),$
 $\dot{y} = \frac{1}{2+c}y(y-1)(4+2c-(4+c)x+2cy+c^2y)$;
 - 12) $\dot{x} = x(x-1)(ax-1),$
 $\dot{y} = -\frac{1}{9a}y(18a-9a(1+a)x+6f(1+a)y-9afxy+2f^2y^2)$;
- where $abcdf(a-1)(c+2)(d+2) \neq 0$ and $a, b, c, d, f \in \mathbb{R}$.*